

The hanging weight is object 1 (mass $m_{1}$ )
The cart is object 2 (mass $\mathrm{m}_{2}$ )
The luggage container is object 3 (mass $m_{3}$ )
What is the mass of the hanging weight as a function of the mass of the cart, the luggage container, the angle of the ramp, and the coefficient of static friction so that the luggage container and the cart have the same acceleration?
Approach: Use Newton's $2^{\text {nd }}$ Law to relate the forces on each object to its acceleration and mass. All 3 objects have the same acceleration if the container does not fall off the cart.

From Newton's $3{ }^{\text {rd }}$ Law the frictional force of the cart on the container equals the frictional force of the container on the cart. Also the normal force of the cart on the container equals the normal force of the container on the cart.

Since we want the container to move with the cart, it must have the same acceleration as the cart. Since the surface of the container does not move relative to the surface of the cart, the frictional force is static friction.

Assume a massless cable and massless, frictionless pulley. The cable exerts the same force at both ends.

Choose a coordinate system with one axis along the ramp.
Free body diagrams


Hanging Weight
$\sum \mathrm{F}_{\mathrm{u}}=\mathrm{m}_{1} \mathrm{~g}-\mathrm{T}=\mathrm{m}_{1} \mathrm{a}$

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$f_{s}=\mu_{s} F_{n 3}$ for maximum static frictional force

Target: $\mathrm{m}_{1}$
Plan
Find $\mathrm{m}_{1}$
$\mathrm{m}_{1} \mathrm{~g}-\mathrm{T}=\mathrm{m}_{1} \mathrm{a} \quad 1$
Find T
$T-\mu_{\mathrm{s}} \mathrm{F}_{\mathrm{n} 3}-\mathrm{m}_{2} \mathrm{~g} \sin \theta=\mathrm{m}_{2} \mathrm{a}$
unknowns
$\mathrm{m}_{1}$
T, a
$2 \quad \mathrm{~F}_{\mathrm{n} 3}$
Find $\mathrm{F}_{\mathrm{n} 3}$
$\mathrm{F}_{\mathrm{n} 3}-\mathrm{m}_{3} \mathrm{~g} \cos \theta=0$
3
Find a
$\mu_{\mathrm{s}} \mathrm{F}_{\mathrm{n} 3}-\mathrm{m}_{3} g \sin \theta=m_{3} a$
4 unknowns, 4 equations. Ok to solve.
Execute:
[4] $\mu_{\mathrm{s}} \mathrm{F}_{\mathrm{n} 3}-\mathrm{m}_{3} g \sin \theta=\mathrm{m}_{3} a$

$$
\frac{\mu_{\mathrm{s}} \mathrm{~F}_{\mathrm{n} 3}-\mathrm{m}_{3} \mathrm{~g} \sin \theta}{\mathrm{~m}_{3}}=\mathrm{a} \text { put into } 1 \text { and } 2
$$

[1] $\mathrm{m}_{1} \mathrm{~g}-\mathrm{T}=\mathrm{m}_{1} \frac{\mu_{\mathrm{s}} \mathrm{F}_{\mathrm{n} 3}-\mathrm{m}_{3} \mathrm{~g} \sin \theta}{\mathrm{~m}_{3}}$
[2] $T-\mu_{\mathrm{s}} \mathrm{F}_{\mathrm{n} 3}-\mathrm{m}_{2} \mathrm{~g} \sin \theta=\mathrm{m}_{2} \frac{\mu_{\mathrm{s}} \mathrm{F}_{\mathrm{n} 3}-\mathrm{m}_{3} g \sin \theta}{\mathrm{~m}_{3}}$
[3] $\mathrm{F}_{\mathrm{n} 3}-\mathrm{m}_{3} \mathrm{~g} \cos \theta=0$

$$
\mathrm{F}_{\mathrm{n} 3}=\mathrm{m}_{3} \mathrm{~g} \cos \theta \quad \text { put into } 1 \text { and } 2
$$

[1] $m_{1} g-T=m_{1} \frac{\mu_{s} m_{3} g \cos \theta-m_{3} g \sin \theta}{m_{3}}=m_{1} g\left(\mu_{s} \cos \theta-\sin \theta\right)$
[2] $T-\mu_{s} m_{3} g \cos \theta-m_{2} g \sin \theta=m_{2} \frac{\mu_{s} m_{3} g \cos \theta-m_{3} g \sin \theta}{m_{3}}=m_{2} g\left(\mu_{s} \cos \theta-\sin \theta\right)$
$T=\mu_{s} m_{3} g \cos \theta+m_{2} g \sin \theta+m_{2} g\left(\mu_{s} \cos \theta-\sin \theta\right) \quad$ put into 1
$m_{1} g-\mu_{s} m_{3} g \cos \theta-m_{2} g \sin \theta-m_{2} g\left(\mu_{s} \cos \theta-\sin \theta\right)=m_{1} g\left(\mu_{s} \cos \theta-\sin \theta\right)$
$m_{1} g-m_{1} g\left(\mu_{s} \cos \theta-\sin \theta\right)=\mu_{s} m_{3} g \cos \theta+m_{2} g \sin \theta+m_{2} g\left(\mu_{s} \cos \theta-\sin \theta\right)$
$\mathrm{m}_{1}=\frac{\mu_{\mathrm{s}} \mathrm{m}_{3} \cos \theta+\mathrm{m}_{2} \sin \theta+\mathrm{m}_{2}\left(\mu_{\mathrm{s}} \cos \theta-\sin \theta\right)}{1-\left(\mu_{\mathrm{s}} \cos \theta-\sin \theta\right)}$
$\mathrm{m}_{1}=\frac{\mu_{\mathrm{s}} \mathrm{m}_{3} \cos \theta+\mathrm{m}_{2} \mu_{\mathrm{s}} \cos \theta}{1-\left(\mu_{\mathrm{s}} \cos \theta-\sin \theta\right)}$
$m_{1}=\left(m_{3}+m_{2}\right) \frac{\mu_{\mathrm{s}} \cos \theta}{1-\left(\mu_{\mathrm{s}} \cos \theta-\sin \theta\right)}$

Evaluate:
Units are ok since the sum of two masses has units of mass and everything else in the equation has no units.
$m_{1}$ depends on the sum of $m_{2}$ and $m_{3}$. This is not unreasonable since if either the mass of the cart or the mass of the container increased, the mass of the hanging weight would have to increase it you wanted to keep the same acceleration.

If the angle of the ramp with the horizontal were 90 degrees, $\mathrm{m}_{1}$ would be 0 . This is not unreasonable since at 90 degrees, the cart and the container would be going straight down. They would move together if they were in free fall (both with the acceleration g). Thus the cable should not pull on them at all. This requires no hanging weight $\left(\mathrm{m}_{1}=0\right)$.

